POS AV 510

IMMEDIATE ANSWERS FROM AIRBORNE DIRECT GEOREFERENCING

POS AV is the foremost commercial GNSS-inertial solution for airborne Direct Georeferencing. Used with digital cameras, film cameras, LiDAR systems, SAR systems, and digital scanners, POS AV precisely measures aerial sensor position and orientation hundreds of times each second, accounting for all motion variables at the exact moment of data capture. In real time or refined in post-processing with the highly productive POSPac Mobile Mapping Suite (MMS) software, data is used to accurately georeference sensor data to the Earth or local mapping frame without ground information, eliminating time-consuming aerotriangulation steps. POS AV is ideally suited to support precision mapping work, especially in inhospitable environments and in rapid response capacities where ground control data may be unavailable or physically impossible to collect.

POS AV integrated precision GNSS with inertial technology is supported by Applanix' industry-leading expertise and a continuous dedication to technological innovation. Offering a streamlined and automated data workflow with built-in quality control features, POS AV improves productivity in all aerial mapping applications.

As Applanix is a Trimble Company (NASDAQ: TRMB), POS AV is unique in the marketplace with its ability to receive the Trimble CenterPoint© RTX™ Correction Service. Using RTX, POS AV delivers significant benefits including higher accuracy and speed, lower cost, more uptime, and greater reliability.

Key Features

- ▶ High-performance, survey-grade multi-frequency GNSS receiver
- ▶ Compact, low-power, lightweight, rugged construction
- ▶ High-performance, low profile FAA certified GNSS-L Band antenna
- ▶ Full in-air alignment support
- ▶ Embedded Omnistar SBAS correction service
- ▶ Trimble CenterPoint© RTX™ correction service available
- ▶ Simple to use and operate with auto-log and auto-start functions
- ▶ POSPac MMS post-processing software bundle includes Carrier Phase DGPS processing, Integrated Inertial/GNSS processing, and optional photogrammetry tools for EO generation, IMU boresight calibration and quality control

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PERFORMANCE SPECIFICATIONS

POS AV Absolute Accuracy Specifications[1] (RMS)

POS AV	510 SPS	510 RTX[3]	510 PP-RTX[4][5]	510 SmartBase Post-processed[4]
Position (m)	1.5 H	0.05 H	0.03 H	0.02 H
	3 V	0.1 V	0.06V	0.05 V
Velocity (m/s)	0.050	0.050	0.005	0.005
Roll & Pitch (deg)	0.008	0.008	0.005	0.005
True Heading[2] (deg)	0.070	0.040	0.010	0.010

POS AV Relative Accuracy

POS AV	510
Noise (deg/sqrt(hr))	0.02
Drift (deg/hr)[7]	0.50

SYSTEM SPECIFICATIONS

Computer System

Component	Dimensions (L x W x H) mm	Weight kg	Power (incl IMU)	Temperature c	Altitude[8] m
PCS Standard	169x186x68	2.4	18-34 Vdc, 59 W Max	-20 to +55	0 to 7,620

Inertial Measurement Unit (IMU)

Type	Range	Dimensions (L x W x H) mm	Operational Temperature c	Weight kg
IMU-91[9]	+/- 10g, +/- 490 dps	116x116x108 (in tophat, provided)	-45 to +55	0.98

Global Navigation Satellite System (GNSS)

Option	Signals	Data Rate
GPS-19	GPS: L1 C/A, L2C, L2E, L5 GLONASS : L1 C/A , L2 C/A, L3 CDMA[11] GALILEO[10]: E1, E5A, E5B, E5AltBOC, E6[11] BeiDou: B1, B2, B3[12] QZSS: L1 C/A, L1S,L1C, L2C, L5,LEX IRNSS: L5 SBAS: L1 C/A and L5 MSS L-Band: Trimble CenterPoint RTX	5 Hz (raw)

ETHERNET INPUT/OUTPUT

Parameters . . . . Time tag, status, position, attitude, velocity, track and speed, dynamics, performance metrics, raw IMU data (at IMU rate), raw GNSS data

Display Port . . . . Low rate (1 Hz) UDP protocol output

Control Port . . . . TCP/IP input for system commands

Primary Port . . . . Real-time (up to 200 Hz) TCP/IP protocol output

Secondary Port . . . . Buffered TCP/IP protocol output for data logging to external device

LOGGING

Parameters . . . . Time tag, status, position, attitude, velocity, track and speed, dynamics, performance metrics, raw IMU data (at IMU rate), raw GNSS data

Media . . . . External: Removable 8 Gbyte Flash Disk (2 supplied) Internal: Embedded 4 Gbyte Flash Disk for redundant logging

RS232 NMEA ASCII OUTPUT

Parameter . . . . NMEA Standard ASCII messages: Position ($INGGA), Heading ($INHDT), Track and Speed ($INVTG), Statistics ($INGST)

Rate . . . . Up to 50 Hz (user selectable)

RS232 HIGH RATE BINARY OUTPUT

Parameter . . . . User selectable binary messages: Time, position, attitude, speed, track, PAV30 output, Yaw Drift Correction

Rate . . . . Up to IMU Data Rate (user selectable)

RS232 INPUT INTERFACES

Parameter . . . . Gimbal encoder input, AUX GPS Input (RTK, NavCom RTCM104 DGPS Corrections Input

Rate . . . . 1 to IMU Data Rate

OTHER I/O

1PPS . . . . 1 pulse-per-second Time Sync output, normally high, active low pulse

Event Input (6) . . . . Six time mark of external events. TTL pulses > 1 ms width, max rate 100 Hz

USER SUPPLIED EQUIPMENT

PC for POS Controller and Operator Client Ssoftware
- Atom 1.6 GHz or equivalent (minimum)
- Intel Graphics media accelerator 500 or equivalent (minimum)
- 2 GB RAM, 32 GB HDD (minimum)
- Ethernet adapter (RJ45 100 base T), USB Port
- Windows 7

PC for Mission Planning and optional POSPac Post-processing
- Pentium 4 (32 bits) at 2 GHz or equivalent (recommended minimum)
- 1 GB RAM, 100 GB Free disk space (recommended minimum)
- 2 X USB 2.0 ports for security keys
- Internet Access (for installation, DEM download, optional SmartBase processing
- Windows 7

[1] Typical performance. Actual results are dependent upon satellite configuration, atmospheric conditions and other environmental effects
[2] Typical mission profile, max RMS error
[3] Trimble RTX service, typical airborne results, subject to regional coverage. Subscription sold separately
[4] POSPac MMS
[5] Post-processed CenterPoint RTX, typical mission performance. Subscription sold separately
[6] May require local gravity model to achieve full accuracy
[7] Attitude will drift at this rate up to a maximum error defined by absolute accuracy in table above
[8] Unpressurized operation
[9] These IMUs are exportable worldwide subject to statutory export declarations, and standard restrictions relating to certain international destinations. Contact your Applanix representative for further information
[10] Developed under the License of European Union and European Space Agency
[11] There is no official version GLONASS L3CDMA or Galileo E6 ICD. The current tracking capability is based on publicly available information. Full receiver compatibility cannot be guaranteed.
[12] The firmware of this product is designed for BeiDou B3 compatibility (trial version) and its firmware will be enhanced to fully support such new signal as soon as official ICD becomes available.

Specifications subject to change without notice.

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