# **Specifications**

Angular stabilization ranges:	
- Pitch (at 0° roll):	≤± 10.5°
- Roll (at 0° pitch):	≤± 10.5°
- Yaw (drift):	≤± 10.5°
Taw (diffe).	3± 25.0
Residual angular rate of the horizontal axis1:	< 0.5°/s rms
Deviation from perpendicular <sup>1</sup> :	
- Without IMU support with feature 'Performance Boost'	≤ 0.3° rms
- With IMU support <sup>2</sup>	≤ 0.08° rms
Interface	RS 232
Payload	0 35 kg
Operational voltage	28 VDC (24 30 VDC)
Power consumption at 28 VDC	30 W rms / peak 120 W
Recommended pre-fuse	15 Amp fuse
Operating temperature	-25 °C +60 °C
Storage temperature	-40 °C +85 °C
Useable diameter	270 mm
	27011111
Mass	14 kg
Wass	14 kg
Dimensions DSM 400	Length Width Height
(regular leveling positions)	460 430 165 <sup>3</sup>
	mm mm mm
Applied standards	RTCA DO-160-G,
	EUROCAE-14G, ISO 7137,
	2006/42/EC Machinery

#### **Custom-Made Precision**



Space for your notes





<sup>3</sup> Minimum: 131 mm/ Maximum 199 mm







**DSM 400** 

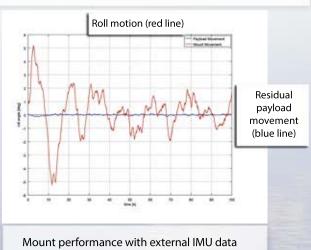


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# **Features/Advantages**

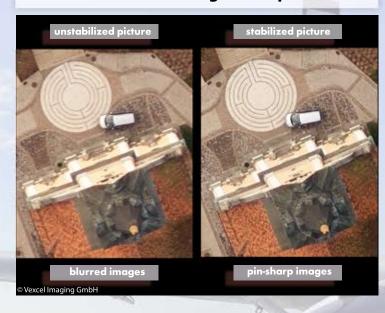
- Powerful Mount for medium format cameras and sensors
   High payload/minimum weight
- Drastic reduction of angular ratesImage motion reduction
- Leveling optionPossibility of using external IMU data (see data example)
- Independent operation
  Without external IMU possible
- Passive Vibration Isolation RingDecoupling of high frequency oscillations
- Applied standards:> EUROCAE-14G, RTCA/DO-160G, ISO 7137, 2006/42/EC Machinery
- SOMAG Mount Control App to setup the best performance for your device and monitor various parameters

#### **Performance Example**

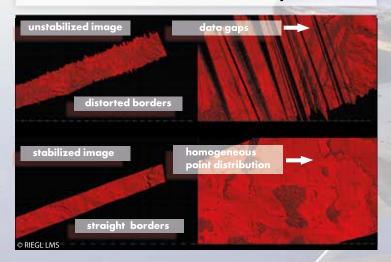


## **Data Examples**

#### **Aerial Image Example**



#### **Aerial LiDAR Data Example**



## **Application Examples**

Phase One 190MP

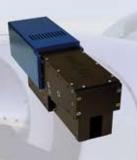
Riegl VUX-1LR





**NEO VNIR - 1800** 

Itres MicroCASI 1920





... ANY OTHER SENSOR IS POSSIBLE!

**DSM 400** 

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